

Determinism, predictability and open-ended evolution: lessons from computational emergence

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1 **Abstract** Among many properties distinguishing emergence, such as novelty,
2 irreducibility and unpredictability, computational accounts of emergence in terms of
3 computational incompressibility aim first at making sense of such unpredictability.
4 Those accounts prove to be more objective than usual accounts in terms of levels of
5 mereology, which often face objections of being too epistemic. The present paper de-
6 fends computational accounts against some objections, and develops what such notions
7 bring to the usual idea of unpredictability. I distinguish the objective unpredictability,
8 compatible with determinism and entailed by emergence, and various possibilities of
9 predictability at emergent levels. This makes sense of practices common in complex
10 systems studies that forge qualitative predictions on the basis of comparisons of sim-
11 ulations with multiple values of parameters. I consider robustness analysis as a way to
12 ensure the ontological character of computational emergence. Finally, I focus on the
13 property of novelty, as it is displayed by biological evolution, and ask whether com-
14 puter simulations of evolution can produce the same kind of emergence as open-ended
15 evolution attested in Phanerozoic records.

16 **Keywords**

17 1 Introduction

18 Recently, an account of emergence in terms of computational compressibility has been
19 proposed by authors such as Bedau (1997, 2008), Holland (1998) and Crutchfield
20 (1994, 2002). This account, centered on computer science rather than on a view of a
21 multilayered ontology for the physical world, had the advantage of being objective in

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22 the sense that it does not make the property of being emergent (or not) dependent upon
 23 the cognitive capacities or explanatory strategies of the human subject. Two related
 24 criticisms could, however, be raised against it: The first one concerns its involve-
 25 ment within the practice of computer simulations; the second one is the worry that
 26 it might make too many things emergent. In a word, one might concede that compu-
 27 tational emergence makes sense of phenomena whose simulation involves emergent
 28 processes in the sense that they will not allow predictions, but cannot account for
 29 other characteristics usually related to emergence such as novelty, order or downward
 30 causation. In this paper, I will start by defending the account against some objections
 31 by showing how the account of unpredictability in models can entail accounts of the
 32 other dimensions of emergence. Then I will discuss what such an idea of emergence
 33 involves concerning predictability in general, and its relation with determinism. I will
 34 show that it allows different kinds of predictability, and therefore makes sense of the
 35 practice of qualitative predictions in the study of complex systems. The last section
 36 will consider the general issue of predictions in evolutionary theory, and therefore
 37 revisit the debates about open-ended evolution and classifying the kinds of evolution
 38 in biology and in artificial life (ALife).

39 2 Emergence: the concept and its instances

40 Among characters that entitle something—a property, a state, a process, or whatever—
 41 to be emergent are novelty, irreducibility, unpredictability and downward causation
 42 (e.g., Silberstein 2002; Chalmers 2006; Newman 1996). Authors frequently insist on
 43 “unpredictability” because the core idea of emergence involves that some phenomenon
 44 or property of a system, though not transcendent, cannot, in some form or another, be
 45 “derived” from the laws of nature and description of the “elementary” properties of this
 46 system. Specifications of this idea include characterizing what ‘derivation’ and ‘ele-
 47 mentary’ mean; “prediction” is arguably a kind of derivation of a state of affairs, and
 48 “elementary properties” may often mean the properties of parts of a system. Numerous
 49 accounts of emergence have been centered on irreducibility, trying to capture the idea
 50 that some property of one level of a system is irreducible to properties of a lower level,
 51 or that properties of a whole system cannot be reduced to properties of parts (e.g.,
 52 Wimsatt 2007; Wilson forthcoming). Yet many of those accounts face the critique that
 53 they grasp something which obviously depends on the explanatory framework of the
 54 cognitive subjects, which for instance decide the relevant parsing of the system into
 55 levels. This gave rise to the worry that emergence is an epistemological property, and
 56 in no ways ontological (Silberstein 2002). The story of British emergentism, whose
 57 paradigm of emergent properties was chemical bonds, and which has been refuted
 58 when the progress of science explained this property away through quantum physics,
 59 is typical in this regard (McLaughlin 1992).

60 Recently, prospects of having a non-epistemic account of emergence arose in the
 61 wake of computer science. Genetic algorithms (Holland 1998), cellular automata
 62 (Bedau 2003; Crutchfield and Hanson 1993; Crutchfield 2002) and agent-based mod-
 63 elling (Epstein 1999) provide a field in which to discuss criteria of emergence that
 64 are rigorous and may have the rigidity of mathematical properties. Such accounts can

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65 be framed under the name of computational emergence (Humphreys and Huneman
66 2008). The basic idea is that a computational simulation process is emergent if and
67 only if its result cannot be reached except by running the whole simulation; in other
68 words, one cannot compress the simulation.¹ The interest of such a criterion is that
69 emergence in this perspective is proved to be objective, in the sense that it does not rely
70 on our epistemic capacities. In effect, the differences between computational classes
71 do not depend upon the abilities of the mind exercising the computation; therefore
72 they are objective and cannot be dissipated through the improvement of our mathe-
73 matical skills (Huneman 2008b). Note that this account of emergence first draws upon
74 the property of unpredictability, which is addressed by logical demonstrations of the
75 computational difference between classes of automata (Buss et al. 1992).

76 However, one could argue that such a concept of emergence cannot be the whole
77 story, since it concerns only simulations, and does not touch upon actual causes in
78 the world (Corning 2002).² However, the point of providing a computational view
79 of emergence is precisely about figuring out a *concept* of emergence that cannot be
80 identified, in last analysis, to an epistemic weakness. Another question is *whether*
81 this concept is *instantiated* in the world, and this entails the issue of the relationships
82 between simulation, or computational models, and processes in nature. But still, it
83 might be that this very concept of emergence entails something about causes (as I
84 argued in Huneman 2008a),³ whether or not it is instantiated in the world. This means
85 that, if something in the world falls under this concept, it will display some specific
86 causal properties. (Sect. 4 below addresses the issue of how we know whether some
87 real system or process actually instantiates the concept).

88 Another worry is that even if unpredictability were accounted for in this way, it
89 would not be equal to emergence, since many unpredictable features are not at all
90 interesting. Among those features, for instance, we could find random sequences, and
91 such a fact is at odds with our intuitive understanding of emergence. I tried to meet
92 this objection in various ways (Huneman 2008a, b), and will summarize this argument
93 here.

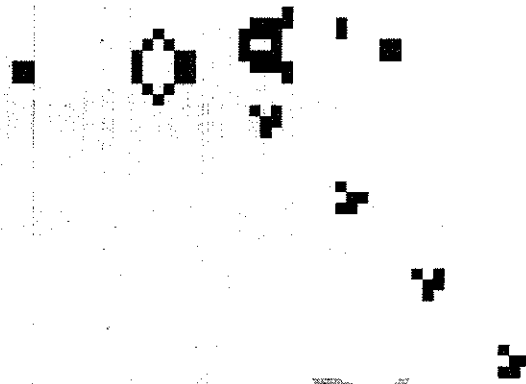
94 First, consider cellular automata (CA) like the Game of Life. Some of these display
95 computational incompressibility, so let's take an incompressible instance of a Game
96 of Life, and keep it running. The whole point of incompressibility is that, while there
97 is a deterministic rule so that one can go from a set of cells $C(i - j, i + j)^n$ to the
98 state of cell Ci^{n+1} , there is no shortcut to go from $C(1, M)^n$ to $C(1, M)^{n+1}$ (M being

¹ Proving that some simulation cannot be compressed is a difficult issue, and indeed Chaitin's results in complexity theory state that this problem is unsolvable. But this concerns our grasp on compressibility, which does not affect the question of whether incompressibility provides a satisfying criterion of emergence. If this is the case, then the trouble of establishing incompressibility would simply mean that we can have no certitude that a process is indeed emergent, only very probable judgments.

² The objection was addressed to a Holland-style account of emergence: "Consider Holland's chess analogy. Rules or laws have no causal efficacy; they do not in fact "generate anything". They serve merely to describe regularities and consistent relationships in nature. These patterns may be very illuminating and important, but the underlying *causal agencies* must be separately specified (though often they are not)" (Corning 2002, p. 26).

³ The argument is basically that within a given simulation counterfactual dependencies hold between sets of states of cells at various steps, which therefore means that causal relationships (*sensu* Lewis 1973) are at stake within it.

Fig. 1 Game of Life, “gospel glider gun” throwing gliders. The moving sets of cells called gliders takes successive positions along the diagonal; the position of a glider at step n counterfactually depends on its position at step $n-m$, at least for a period of the simulation



99 the number of cells) or from n to the whole state of $C(1, M)^n$. However, among the
 100 cellular automata, it might well be that some display gliders, glider guns or all this
 101 fauna of digital creatures familiar to computer scientists. This means that, though still
 102 incompressible, there is another way to describe the Game of Life which relies on
 103 counterfactual dependencies between sets of sets of cells at various steps.⁴ A glider
 104 can indeed be characterized as a set of sets of cells; gliders have typical behaviors,
 105 so that if at step n the glider is at one point, analysis of the cellular automaton may
 106 entail that it will be somewhere else a while after (after N steps, let's say). One can
 107 then claim that, on the background of the rules of the automaton, the glider would
 108 not be where it is at step $n + N$ if it had not been where it was at step n (Fig. 1).
 109 This is a counterfactual dependency, and it illustrates the fact that even in cellular
 110 automata showing computational incompressibility, some regularities of this type can
 111 be produced.

112 The class of automata that, in addition to being computationally incompressible
 113 processes (“weakly emergent” *sensu* Bedau), display such counterfactual dependenc-
 114 es between sets of sets of cells, match our expectations concerning the concept of
 115 emergence (namely, both unpredictability and a kind of “order”)—and I thereby call
 116 them “robustly emergent.” The global behavior of such an automaton, far from being
 117 random, displays global regularities that were not implemented in its first designing
 118 or description. This meets our intuitive idea that emergent features should exhibit a
 119 kind of order not reducible to properties of the parts.

120 Bedau (2008), defining weak emergence, insists that it is both dependent (on the
 121 properties of the elementary building blocks) and autonomous. The irreducibility of
 122 entities involved in novel counterfactual dependency exactly fits his definition. Here,
 123 “irreducible” does not mean that it is something ontologically different from the basis
 124 of the entities (in this case, the cells of the CA). In fact the gliders, and all the global-
 125 level entities emerging within the automaton used to track counterfactual dependencies
 126 within it, are not superadded. Because they are produced by the building blocks, they
 127 are the deterministic effects of the building blocks’ movement (see Epstein 1999 for
 128 the same demonstration about agent-based models). However, they are irreducible in
 129 the sense that deriving the exact position and movement of an entity like a glider

⁴ A more precise characterization, in terms of counterfactual dependencies between internal properties of the CA defined by disjunctions of sets of states of cells, is given in Huneman (2008a).

H states
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130 from the rules and position of the initial cells is precisely incompressible; there is
 131 no shortcut (because the whole emergence of gliders was incompressible). In this
 132 sense emergence does not oppose reductionism; ~~causal~~ processes take place in the *H the*
 133 building blocks or the cells, according to their rules, and they completely determine
 134 the behavior of the automaton. However, a more explanatory set of counterfactual
 135 dependencies—so causal relationships, in a weak sense of causation—is produced
 136 through the emergent, incomputable process.⁵ Thereby, notwithstanding the compu-
 137 tational incompressibility proper to the simulation, we can still look for macrostates
 138 that could be predictors of what follows, and then parameters that would define a class
 139 of those macrostates – in the sense of maximized “efficiency of prediction” defined by
 140 Shalizi (Shalizi and Moore 2003; Shalizi and Crutchfield 2008) in the context of his
 141 conception of macrostates. So the claim here is that robust computational emergence
 142 includes some *specific causal patterns*, and is not only formal; Sect. 4 will examine
 143 under which conditions those causal patterns exhibited by computer simulations match
 144 real causation in nature.

145 I will now turn to the consequences of such a complete concept of emergence
 146 (computational irreducibility and counterfactual dependencies between global-level *ital*
 147 entities) for the idea of predictability.

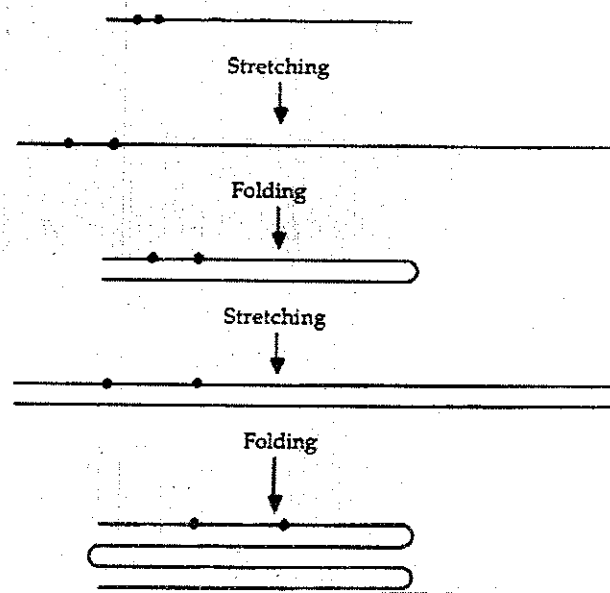
148 3 Emergence, predictability and determinism

149 One interesting point about this view of robust emergence is that it disentangles the
 150 two concepts of determinism and predictability, in a formal manner. Cellular automata
 151 are purely deterministic; yet, some processes might be incompressible, which means
 152 that they yield unpredictable results.

153 If we cash out the idea of predictability, it intuitively means the following. Imagine
 154 a system, even a deterministic one, with a given initial state (i), i.e., an initial value of
 155 the descriptive state variables or initial position in the state space, and a small range
 156 (d) of values around those initial values. This system allows predictions if the final
 157 values it reaches, starting from all different initial values in $[i - d; i + d]$, are in a
 158 range $f(d)$ which is not too much larger than the range (d) of initial values. If not, it
 159 means that the margin of error (represented here by d) of our measurements of those
 160 initial values will not ensure that the final result yielded by calculating the final state
 161 is in a same or analogous margin of error, so there will be no possible prediction. The
 162 baker’s transformation (Fig. 2) provides a famous example of a system which is clearly
 163 deterministic, but for which two arbitrarily close points in the initial state will have at
 164 some step n a distance which will be very large, but they will still be able to get very
 165 close at some remote step $n + m$. Any margin of error around a point A initially will
 166 render prediction of the final state of A impossible. Interestingly, although predicting *1/a*
 167 is related to our epistemic capacities, this condition for being predictable or not is a *H the system*

⁵ One must note that this account of emergence in terms of a new explanatory level that is not computationally (or analytically) involved in the explanatory practices for the building blocks level comes close to the way Batterman (2002) characterizes emergence in terms of gaps between explanatory regimes (which is the way he solves the riddle of downward causation).

Fig. 2 The baker's transformation—one of the simplest cases of unpredictability in deterministic systems. At each step the line is stretched to twice its length and then folded. Two points randomly chosen, no matter how close they are, will at an arbitrary step in the future be arbitrary far from each other. This renders any prediction as to the fate of one initial point impossible (given that an interval around it, as small as it can be, still yields future states that lie in an arbitrarily extended interval)



168 property of the system, so it is *objective*. Famously it is expressed by the notion of
169 sensitivity to initial conditions.

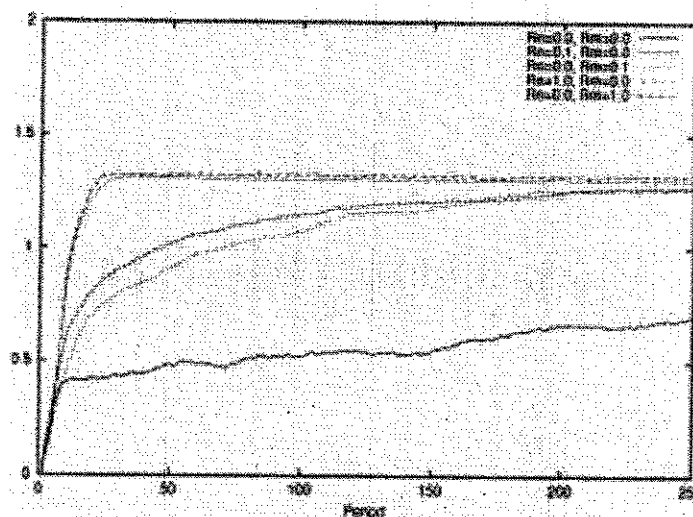
170 In the case of computational emergence, a logical result shows that when in some
171 set of logical automata the initial state is changed, there is no polynomial function of
172 the predicted result that would yield the correct prediction for the subsequent new final
173 state (Buss et al. 1999). On the contrary, it is at least an exponential function of this
174 result, which means that no computation can correct the prediction. So those determin-
175 istic systems like CA that display emergent behavior are not predictable, although they
176 are deterministic. In stochastic computer simulations like some genetic algorithms, the
177 same criterion of emergence can be applied; this means that the property of unpredict-
178 ability is orthogonal to the difference between determinism and stochasticity, while it
179 is also an objective property of systems.

180 Now, if we remember that computational emergence still allows discriminating a
181 class of robustly emergent processes, what does it mean for predictability? The issue
182 is all the more difficult since, though genetic algorithms may sometimes be emergent
183 in this sense, they are somehow predictable because they are often designed to build
184 a predicted result. In this case, the distinction is straightforward: Though the global
185 result is predictable, the pathway toward it is not, since the way the program reaches
186 its optimum is precisely incompressible.

187 What *in general* corresponds to this notion of pathway unpredictability? Consider-
188 ing the counterfactual dependencies (such as between the gliders) actually yields some
189 predictions in emergent, hence unpredictable, processes. So *prima facie*, if you want to
190 track down the trajectory of one cell in a CA satisfying the incompressibility criterion
191 (for more details on such criteria see Hovda 2008), it will quickly become computa-
192 tionally intractable and thus impossible. The very definition of unpredictability is met
193 here: Changing slightly the initial state of a cell's neighbor from i to i' will be such
194 that no computable function of the final state f_i will give you the modified final state
195 $f_{i'}$ of this cell. This view can easily be generalized: In a robustly emergent process,

196 the trajectory of one point, or one micro-element of the system, is not predictable.
 197 However, as I show here, some predictions—here called macro-predictions—can be
 198 reached at the level of global entities whose counterfactual dependencies emerge in
 199 the course of the process. Israeli and Goldenfeld (2004) made the point that all the 2-D
 200 CA (rules 1–256) could be coarse-grained into other CA. You just have to take sets of
 201 cells x_j as one cell X_j , and project the rule that changes x_i according to the state of
 202 their neighborhood onto a rule changing X_j according to the state of its neighbours
 203 $X_{j'}$. Many computationally reducible CA appear to be reducible at a coarse-grained
 204 level. For example, the CA with rule 146 has a coarse-grained version with rule 128,
 205 which is of class II, so computationally reducible.

206 One can roughly distinguish between agent-based models (ABM), or in general
 207 computer simulations, which embody equations of a theory explaining a phenomenon
 208 (a), and ABM or simulations that just take as rules some plausible regularity, observed
 209 at a large scale (b). A famous example of the latter category is of course Reynolds's
 210 simulation of the movement of flocks of birds or schools of fish (1987). The gener-
 211 erative rules are hypothesized on the basis of what is observed (birds, or "boids" in
 212 the simulation, have three simple rules, like fly in the direction of the mean direction
 213 of the others, do not go too far from the immediate neighbors, etc.). Another exam-
 214 ple of the latter category (b) for elaborating macro-predictions comes from Epstein
 215 (2002), in his "generative social science" project of designing agent-based models
 216 for social phenomena. He created ~~agent-based models~~ for rebellion and social upris-
 217 ings, whose agents are individuals, and parameters are the level of legitimacy of the
 218 government and the level of oppression. He varies the parameters, and the behavior
 219 of the agents obeys just a few rules, like the intuitive rule that agents will not easily
 220 rebel if nobody else does, but likely will if many of their neighbors are uprising. The
 221 results are striking to various degrees, depending on the levels of the parameters and
 222 above all the kind of change those parameters undergo; all simulations display a few
 223 characteristic kinds of patterns. For example, when the legitimacy of governments
 224 drops, what is crucial for the likelihood of uprising is the speed of this fall, not the
 225 width. So ABM here allows one to predict likelihood and patterns of uprising on the
 226 basis of the values and changes of two global parameters; the ranges of values and
 227 types of behaviors are indeed predictors of the global uprising behavior in the set of
 228 agents. Another simulation in the field of social sciences shows the same possibil-
 229 ity of macro-predictions of emerging behaviors (see Tassier's (2004) study on fads).
 230 The outcomes of simulations, here, might display some emerging general behaviors
 231 of agents—namely, fads. Then, according to the ranges of variables, we will witness
 232 an extension of this pattern of behaviors or, more interestingly, some life cycles for
 233 those collective behaviors; those patterns adequately represent the empirically attested
 234 phenomena proper to fashion. The resulting patterns can be classified according to the
 235 following categories: "If agents imitate each other in order to express an affiliation,
 236 there are at least three phenomena that may develop: First, all agents in the popula-
 237 tion may coordinate on one alternative. Second, another type of stable behavior may
 238 develop; agents may separate themselves into stable groups with each group acting
 239 in one particular way, or buying a particular good. Third, stable or unstable cycles
 240 may develop. These cycles are examples of what I am calling fads or fashion cycles"
 241 (Tassier 2004, p. 51). The simulation uses models of networks with connected agents,



Amount of group formation for various network structures.

Fig. 3 Group formation according to probabilities R_m and R_n in Tassier's models of fads (2004). Credits Tassier, Wiley and Son

242 like in Watts (2002), Watts and Strogatz (1998), and Barabasi and Albert (1999). One
 243 of the important parameters for the simulation is the “preference parameters for having
 244 agents of similar idiosyncratic type and high attraction” in the group to which the focal
 245 agent belongs; the other parameters are the probability of having a connection with
 246 some individual not connected to the neighbors, and the probability of having a quick
 247 encounter with individuals of other sub-networks “such as people one notices when
 248 walking down a street that the agent does not know or other random meetings that may
 249 occur” (p. 53). Group formations and cycles of fads (defined by the creation of those
 250 groups) can be predicted through the simulation from the values of those parameters
 251 (see Fig. 3).

252 The simulations exemplified by the above studies achieve the following: Although
 253 trajectories of some agents are not predictable (and this is entailed by computational
 254 emergence), one can run several rounds of simulations and check whether ranges of
 255 values of the state parameters (legitimacy, level of oppression, etc.) will always yield
 256 the same pattern of behavior.⁶ The “pattern” here is exactly what I alluded to with the
 257 example of the gliders: There are dependencies between sets of states of agents, even
 258 if those sets are in each simulation realized variously by the agents (e.g., uprisings
 259 are not always led by the same agents, in the same time, with the same length, in
 260 the same places, etc.). However, the counterfactual dependencies between range of
 261 values, uprisings, their frequency and their succession, are attested by the computer
 262 simulations. The fact that given the initial state of the model—positions of the agents,
 263 values of state variables—one cannot predict the fate of an agent does not preclude
 264 a prediction of general patterns of uprising, based of the counterfactual dependencies
 265 between those patterns (here noted m-regularities), on the one hand, and the range
 266 of values of the initial parameters on the other hand. In those examples, what is at

⁶ On the notion of patterns, see Humphreys (2008), in the framework of cellular automata research.

267 stake is the distinction of several levels of prediction, in processes that are “robustly
268 emergent” (in the sense of computational emergence as defined above).

269 More precisely: Robust emergence implies the possibility of predictions based
270 on the counterfactual dependencies between global level entities (noted here m-pre-
271 dictions). What appears in the present examples is a sort of second-degree macro
272 prediction (here M-prediction), which holds between sets of parameters and sets of
273 global-level entities (which can define some patterns). Now, what is considered is a
274 set of simulations, and the M-predictions relate on the one hand the initial values of
275 the initial states (given the rules of the simulation), and on the other hand those reg-
276 ularities emerging in each simulation. In M-predictions, we are concerned with what
277 is generic in multiple runs of the same simulation with different initial distributions,
278 and different values for the parameters (e.g., the levels of oppression and the trust
279 towards government, in Epstein’s models of uprising). Of course, these M-predictions
280 somehow generalize the m-predictions that are possible in a given simulation on the
281 basis of those emergent m-regularities (in the sense of counterfactual dependencies
282 instantiated by the ones that tie the gliders together, or which link several successive
283 global steps of an uprising process in Epstein’s model).

284 Let us explicate this distinction between levels of prediction. In several simulations
285 (various initial distributions, and possibly various values of initial parameters, as in the
286 case of agent-based modeling), different patterns (with different sizes and positions)
287 emerge. The m-regularities proper to the patterns in a token simulation allow m-predic-
288 tions internal to this token simulation. Their behaviors (in the sense of m-regularities)
289 are likely to be clustered into *more general classes*. (e.g., in runs of a Game of Life
290 with various initial distributions we will have “gliders with glider guns,” “gliders with
291 no glider guns,” etc.). Those general classes in turn can then be related to the *ranges*
292 of the variables (about the initial distribution, or about the parameters for the rules)
293 that determine them. This range is determined by all the values of variables for initial
294 distribution (and/or all the values of parameters for the rules of the simulation) which
295 generate m-regularities likely to be clustered in the same class (e.g., “late uprising,”
296 “uprising resolved,” “no uprising,” etc. in Epstein’s models of social rebellion).⁷

297 Computational emergence entails that changing the value of initial states of cells, or
298 agents, precludes any prediction of the final states of the agents on the basis of the ear-
299 lier knowledge of the initial states—*micro-unpredictability*; but this does not logically
300 entail that concerning the m-regularities those changes will still display such sensitivity
301 to initial conditions. So the unpredictability ontologically proper to those systems—in
302 terms of unpredictability of the trajectories of agents—is however superseded, first by

⁷ One can refer to the notion of attractors in order to understand what is at stake here; basically attractors are those configurations allowing all varieties of a same system (differing by the values of their parameters) to revolve around them in the phase space and display a similar sort of qualitative pattern of behavior. Exploring many simulations therefore allows one to identify the counterfactual dependencies between ranges of values of the parameters and possible attractors, so that the shifts of attractors (“bifurcations”) can be made manifest and related to the changes of values of parameters upon which they depend. The relations between attractors and ranges of parameters defining classes of systems exactly correspond to M-predictions in our case. (Newman 1996 develops an attempt to understand emergence in the light of the notion of strange attractors, usual in chaos theory. I sketch here the reverse conceptual pathway, although both theorizations are related and compatible.)

303 the m-predictions yielded by the m-regularities manifested by global-level entities in
 304 one simulation, and second by the M-predictions yielded by the counterfactual depen-
 305 dencies attested between sets of m-regularities and ranges of parameters in classes
 306 of varied simulations. For example, the emergence of local norms is a m-regularity
 307 involving evolving sets of agents, and is regularly correlated to ranges of values of the
 308 parameters of the simulations in Burke and colleagues' (2006) study of the dynamics
 309 of social norms.

310 This explains why the study of complex systems, whose state equations are often
 311 analytically intractable, can be done through the design of various simulations and their
 312 comparisons. Such comparisons indeed, notwithstanding the unpredictability proper
 313 to those systems, will allow predictions in the sense of connections between ranges
 314 of values of the parameters or variables, and qualitative patterns of behaviors of the
 315 systems. Although such study is experimental, i.e., one has to run many simulations
 316 and try to explore wide ranges of values of parameters, the proper unpredictability of
 317 the system as emergent does not ruin it, in the sense that it would render absolutely
 318 meaningless the inference towards general classes of behaviors.⁸

319 **4 Robustness analysis, relevant causal factors and the instantiations** 320 **of the formal computational concept of emergence**

321 The last worry about computational emergence was that the concept fits only simula-
 322 tions but is not instantiated in the real world, or that we cannot know when it is indeed
 323 instantiated. More precisely, one could argue: This natural process is modeled by a
 324 computer simulation that displays emergent processes, and such emergent character-
 325 istics are absolutely *objective*; fair enough. Computational emergence is also a *causal*
 326 concept (Huneman 2008b; Bedau 2008), so when a computer simulation falls under
 327 it, such model tells us something about the causal structure of the modeled system.
 328 However, who knows whether this simulation is an accurate one? Couldn't the process
 329 be modeled by another, non-emergent simulation, which for the moment we cannot
 330 grasp? An answer can be provided by consideration of the methodology of complex
 331 systems study through qualitative M-predictions, as exemplified above.

332 In such studies, identifying the qualitative patterns of behavior is done by varying
 333 the values of the variables in the simulations, and then running them. Yet one can
 334 also vary the *sets of parameters* used in a simulation. This would probably refine the
 335 predictions (for example, suppose that in Epstein's simulation we add a parameter like
 336 degree of education). However, it might be that some parameters do *not* change the
 337 patterns of behavior.

338 *Robustness analysis* is the method of comparing several models with varied values
 339 of the variables or parameters used, for a given phenomenon. There are two kinds
 340 of robustness analysis, one weaker and one stronger, according to whether you vary
 341 the values of the parameters, or modify the number and nature of the parameters

⁸ Of course, varying the values in order to find how those changes affect the trajectories of one given agent
 will be pointless, precisely because of this unpredictability.

in an ABM

342 themselves (Weisberg 2006a,b).⁹ When the model yields the same predictions and the
 343 same patterns of behavior even if we change some parameters, then it is said to be
 344 “robust.”¹⁰ In this case, even if we were mistaken in identifying the relevant param- H J
 345 eters, our model would still be accurate, and somehow fitting the “causal structure”¹¹
 346 of the target systems, since nothing in its behavior would change when we substituted
 347 other parameters (the relevant ones) for the ones actually used (Levins 1966; Wimsatt H J
 348 2007; Weisberg 2006a).¹²

349 An example of this case is provided by the neutral theory of ecology (Hubbell
 350 2001). In modeling relationships of vicariance, distribution and abundance between
 351 species in a community (species of the same trophic level, e.g., trees), the theory poses
 352 the unrealistic hypothesis that rates of death and birth are the same for all individuals
 353 of all species; this is highly implausible and entails a negation of natural selection.
 354 Actually the model repeatedly correctly predicts distributions, for example of species
 355 of trees in tropical rainforests; abundance distributions of species of trees in the Barrio
 356 Alto rainforest have been accurately modeled in this framework (Hubbell 2001). These
 357 models are often sophisticated simulations, and it is plausible that in many of them
 358 the outcome is *computationally emergent*; moreover such processes display *robust*
 359 emergence, because in the end we have patterns appearing and following each other
 360 in a regular manner, which makes room for the m-regularities I talked about in Sect. 3.
 361 Now, the outcomes of such models often intriguingly match the actual distribution
 362 (Chave 2004; Holyoak and Loreau 2006).

363 Taking natural selection as a parameter defines what ecologists call “niche effects.”
 364 If we incorporate “niche effects” in those models which successfully represent actual
 365 distributions, the fact is that the outcomes will not change much (Bell et al. 2006,
 366 p. 1383; Chave 2004, p. 246). So the model of species abundance distribution in the
 367 tropical rainforest is robust in the sense that adding niche parameters does not change
 368 the outcome; moreover, numerous outcomes of the simulations designed according
 369 to neutral theory (given various initial states) match the patterns displayed by real
 370 systems. From this viewpoint it is plausible that the neutral dynamics, for which the
 371 only parameters are the general parameters of the population (namely the size, the
 372 age of reproduction, etc.), and which mainly occurs because of dispersal limitation,¹³
 373 is causally responsible for the emergent patterns of distribution (Chave 2004). The

⁹ In what follows I will focus mostly on strong robustness analysis.

¹⁰ Above, “robust” emergence means computationally emergent process with robust counterfactual dependencies between macro patterns; here “robustness” concerns a set of models. Those meanings are not identical: We can speak of “robust models of robustly emergent processes” when a model satisfying a robustness analysis displays robustly computationally emergent processes. In order to keep with previous uses in both modeling literature and emergence literature, I kept this unfortunate dual use of a single word.

¹¹ The connection between a robust model and its consistency with the “causal structure” of the system is argued for in Weisberg (2006a,b).

¹² The same reasoning also holds of course for robustness analysis concerning the values of the variables (weak robustness analysis).

¹³ Connectivity of space and number of species yields dispersal limitation, which in turn influences the relative strength of intra- and inter-specific competition, and finally leads to equalizing fitnesses, both inter- and intra-specific (Holyoak and Loreau 2006, p. 1374). This mechanism explains the adequacy of the assumptions of the neutral model.

374 robustness of such neutral models dismisses niche effects as putative causal factors
375 for this outcome.

376 Analyzing the examples involves two important consequences. First, the initial
377 objection about the purely formal character of emergence can be dismissed. Suppose
378 that Epstein's model of civil uprisings is robust. It means that the system modeled—
379 here collectives of people—is captured in its causal structure by the model. So when
380 there is emergence in this model (of course, all the parameter values may not generate
381 emergence in the above sense of robust emergence), the *reality* itself can be said to
382 *display emergent processes* or emergent properties, since this emergence has been
383 made manifest in a robust model of its causal structure. So robustness analysis, here,
384 allows one to rebut an objection based on the fact that someday we might have a better
385 knowledge of the system. Computer simulations of a process which display robust
386 emergence and which have passed the test of robustness analysis can rightly allow
387 us to infer that the real system has emergent features, in a sense which is in no way
388 epistemic, and even if we later learn of other parameters responsible for the behavior
389 of the system which we could insert in a new model. This new model will indeed be
390 similarly emergent, because of the robustness of the family of models considered.

391 The second insight concerns the relevant causal factors. A robust model does not
392 change its global outcome, which maps onto the actual outcome of the system,¹⁴ when
393 we vary variables or parameters. I argue here that the parameters not causally respon-
394 sible for the emergent features are the ones that are not making a difference to the
395 robust model's behavior. Suppose that indeed adding or withdrawing the parameter
396 "education" does not change the qualitative behaviors in Epstein's model of uprising
397 (behaviors are the connections between ranges of values and m-regularities, as stated
398 above). This means that nothing in the m-regularities depends upon such parameter.
399 So whereas those parameters involve many effects in the behaviors of the individual
400 "agents," they must not be held as causes of the qualitative patterns of outcome behav-
401 iors considered here, namely the trends for uprising. Thus, while robustness analyses
402 of models enables one to infer from emergence in simulations to emergence in natural
403 processes, it also allows one to identify the parameters that will be causally relevant
404 in the production of emergent features in the processes (or at least exclude the ones
405 that are not responsible).

406 More precisely, the robustness of the model means that it is not sensitive to adding
407 or withdrawing some parameters. Why is this so? An inference to best explanation
408 gives here the answer. What could possibly explain the insensitivity to other param-
409 eters? In fact, in reality there are always a very large number of parameters for a given
410 system, but parameters are connected such that the effects of some of their values
411 are compensated for by others, so that in the end they are inefficient regarding the
412 outcome. Hence, the insensitivity to change of parameters, on the side of the model,
413 together with the fact that outcomes of the model map onto real situations, would mean
414 that those connections are captured through the model, which means in turn that it is
415 somehow connected to reality. In this sense, the best explanation for the parameter
416 insensitivity of robust modeling is some connection with the "causal structure" of

¹⁴ There are many ways to define this mapping, but I will not consider this issue here. Suffice to say that the M-predictions from the model are confirmed in many actual instances of the system.

417 reality.¹⁵ Therefore, the consequence, in the case of a robust model displaying emer-
 418 gent processes, is that this model parses the parameters causally responsible for emer-
 419 gent features, and the ones that are not.

420 Generally speaking, the philosophical issue here is reading causal factors off sci-
 421 entific models. When models are equations, it is assumed that the variables in the
 422 equations are the relevant causal factors in reality.¹⁶ Analogously, in the case of com-
 423 puter simulations designed when equations are out of reach or intractable, reading the
 424 causal factors off the model consists in identifying which parameters are constantly
 425 present in a robust modeling of a system. When emergence is displayed in such models,
 426 we have therefore a grasp on the factors responsible for emergent features.

427 The last consequence involves the controversial issue of “downward causation.”
 428 Traditionally emergence also goes with novelty and downward causation. The latter
 429 is the most controversial, and in this context may be explicated by the relationship
 430 between the explanatory force of the global emergent level of m-regularities, and the
 431 level of building blocks, which enable only local explanations. Indeed, the m-regu-
 432 larities, once stated, will somehow constrain the behavior of these building blocks.
 433 If I know that an uprising is likely to happen here (because the parameters are in the
 434 range of values upon which uprising depends), then I know that most of the agents in
 435 these circumstances will often enter into rebellion, even if the uprising is not a cause
 436 but is generated by the acts of the agents. Recognizing this constraint by global-level
 437 m-regularities neither deprives the agents or cells or building blocks of their unique
 438 causal efficacy, nor add other sets of causes and forces acting somehow from above
 439 the agents (see also the critique of strong emergence in ABM by Epstein 1999). So
 440 the value of the parameters is a relevant causal factor (of the uprising), as well as the
 441 acts of the agents. Yet the classical arguments (e.g., Kim 1999) against downward
 442 causation—in terms of overdetermination—do not hold here, because the relationship
 443 between those two categories of causes is not exactly one of levels: The values of
 444 the parameters are not *caused* by the acts of the agents. So we have indeed a case of
 445 “downward causation”—except that precisely because the “levels” relation does not
 446 hold, the term may be inappropriate.

447 As for novelty, the analysis provided here may not be directly illuminating. In order
 448 to develop this last traditional connotation of emergence in the framework of compu-
 449 tational emergence, I consider in the last section a case study, novelty in evolution or
 450 the problem called open-ended evolution.

(see also
Humphreys
1997)

451 5 Novelty: a case study about artificial life and open-ended evolution

452 Evolution of life on Earth shows continual adaptability and innovation. Adaptation
 453 is traditionally explained by natural selection (Brandon 1996; Williams 1966), and
 454 so all genetic algorithms based on natural selection display adaptation. Innovations

¹⁵ Notice that the argument proposed here corresponds to the “inference to best explanation” for scientific realism.

¹⁶ Metaphysically speaking, an argument for that could derive from Quine’s dictum on reality (“to be is to be the value of a linked variable”) and the widely-accepted metaphysical thesis that real entities necessarily have a causal effect.

455 concern novelties such as the wings of insects, the gills of fish or language: They are
 456 a radical qualitative difference in morphology or behaviour, and trigger new phyloge- (Kauffman, 2000)
 457 netic patterns and adaptive radiation (Müller 2002). Some biologists argue that natural
 458 selection alone cannot account for innovation, but only, through cumulative selection,
 459 for continuous adaptation. Processes like developmental scaffolding (e.g., Müller and
 460 Newman 2005; Carroll 2005; Arthur 2001) have been proposed to supplement natural
 461 selection for mutation and recombination here—the bulk of the critique being that
 462 normal mechanisms of variation such as mutation and recombination cannot allow a
 463 selective process that would yield such innovations. The alternative view of evolution
 464 trying to emphasize the role of development, and known as evolutionary developmen-
 465 tal biology or evo-devo, is widely concerned by such issues (Amundson 2005). Other
 466 suggestions have been made for processes responsible for innovations, for example
 467 symbiosis—and some computer algorithmic modelling has helped to understand the
 468 potential for novelty proper to those processes (Watson 2005).

469 In this sense, artificial life¹⁷ could model not only adaptations (in genetic algo-
 470 rithms), but also processes of innovations. Some argue that life on Earth displays
 471 “open-ended evolution” in the sense that innovation is pervasive and also that no limit
 472 can be set to this propensity for novelty. Evolutionary theory can yield predictions,
 473 but unpredictable events are always opening new kinds of possible adaptations— H heating
 474 for instance, evolution of wings is explained by natural selection, but before insects
 475 appeared no one could have predicted that 1 day animals would also be living in / one
 476 the sky, as Kauffman likes to emphasize. Some term this propensity “creativity” MURPHY
 477 (Taylor 2001), others “open-ended evolution.” Anyway, the problem remains: Is arti-
 478 ficial life, which already gives rise to adaptation and some innovations, able to display
 479 open-ended evolution, so that nothing uniquely proper to life on Earth is involved in
 480 this feature of evolution? Or are there several large classes of evolution, all possibly
 481 instantiated by some kinds of computer simulations, among which one class displays
 482 open-ended evolution and includes, as a token, life on Earth, along with other evolu- K S
 483 tion designed by some appropriate ALife design? In this last case, it means that we
 484 could pinpoint the causal factors relevant to open-ended evolution.

485 Such a question of course is entangled with the issue of contingency in evolution.
 486 If evolution is contingent, then it is unpredictable—meaning that some events extrin-
 487 sic to the course of natural selection (such as the fall of an asteroid) triggered major
 488 events within evolution. It is not absolute unpredictability—for example, given the
 489 appropriate hypothesis, e.g., the fall of the asteroid, we could predict some outcomes;
 490 but it is unpredictability within a given model. Gould says that a model of biological
 491 microevolution at the times of the Cambrian would not predict evolution afterwards
 492 because the most relevant cause (the asteroid) is a hypothesis extrinsic to such a model.
 493 On the other hand if evolution is necessary, it means that even if we “replay the tape
 494 of life” (Gould 1989; Fontana and Buss 1994), as in the famous Gouldian metaphor,
 495 we will still find the same kinds of features: mobile entities, detectors, light detec-
 496 tors, motion tracking devices, etc. Basically, the models of evolution elaborated in
 497 the classical modern synthesis theory of evolution (macroevolution extrapolated from

¹⁷ See Langton (1989) for an overview, and Lange (1996) for a philosophical assessment.

498 micro evolution) would be robust against all extrinsic possible circumstances (i.e., on
 499 average natural selection and drift account for what happens). So in the end we would
 500 not have mammals and nervous systems, but we would have creatures able to track
 501 changes in their environment in order to prey and resist parasites. Dennett (1995) calls
 502 this “good tricks.” Running many simulations in artificial life is meaningful under
 503 this hypothesis, because it will display some causal factors relevant to evolution and
 504 the main qualitative patterns of evolution, i.e., the “good tricks” with their patterns
 505 of causal efficiency. The “contingency” issue might be a question of fine-grained vs.
 506 coarse-grained views of evolution. The predictions, if we think of Kauffman’s wings
 507 example, are always possible when some novelty happens. So evolution seems pre-
 508 dictable at a local scale (at least in its gross features), but not at the global scale,
 509 because those novelties are themselves contingent. The two debates (necessity or con-
 510 tingency in evolution, uniqueness of open-ended evolution in life) are not identical,
 511 but are quite related. Open-endedness means the potential for novelties (such as the
 512 wing) that are contingent in a very large-scale view of evolution. Many classifications
 513 have been proposed in the evolutionary computer sciences literature, and these final
 514 paragraphs sketch a survey of them and suggest a synthetic classification based on
 515 the present analysis of the status of algorithmic models and discontinuous evolution.
 516 The consequence of such classification is that it could help us to understand what is
 517 proper to life in our world—in opposition to a would-be evolution by natural selection
 518 in other possible worlds.

519 Those classifications are built, either in a sort of “semantic” perspective (con-
 520 sidering what it means to say that “X is novel”), or from an epistemological point
 521 of view (considering the various cases of robust emergence in the various scientific
 522 contexts).

- 523 • *Semantically*, from the computational point of view, Cariani and Ray (1992)
 524 distinguished syntactic, semantic and pragmatic emergence; Crutchfield (2002)
 525 distinguished emergence in intuitive sense, emergence as patterns newly appear-
 526 ing, and “intrinsic emergence;” Pattee (1989) seems equally inspired when he
 527 indicates “new measurement” as the third and truest kind of emergence.
- 528 • *Epistemologically*, Bedau et al. (1998) distinguished three kinds of emergence:
 529 Class II is “bounded emergence”—Holland’s (1995) GA Echo—as opposed to
 530 class I, no emergence, in an Echo simulation *with no selection* (what they call
 531 “Echo neutral shadow”), and class III is “unbounded emergence,” manifest in the
 532 phanerozoic fossil records (i.e. the history of life). “Bounded” for Bedau and
 533 Packard means that the range of adaptations exhibited is somehow finite, which is
 534 not the case in class III. Contrary to the example of the contingent emergence of
 535 wings and the subsequent colonization of avian space, in Echo, it makes no sense
 536 to speak of another environment likely to be colonized: “Digital organisms” will be
 537 restricted to adapting to computer environments; hence the range of adaptations is
 538 bounded.
- 539 • Channon’s classification is also tripartite, elaborating on his Geb simulation.
 540 (1) artificial selection in the SAGA simulation, (2) natural selection of program
 541 codes in Ray’s Tierra, which seems a now-limited evolution, and (3) less limited

Eventually, to
 Coarse grained
 I S I S
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 they
 I S I S

(Channon
 and Dampier
 1998, 2000)

542 evolution through Channon's "natural selection"¹⁸ in Geb simulation. Hence the
 543 major question about novelty and open-endedness: Is the Channon class 3 in the
 544 latter analysis the same as Bedau and Packard's class III (fossil records, i.e., life)?

545 I would suggest another classification, based on the considerations developed here.

- 546 A. Imagine a simulation with no selection acting like Kauffman's "order for free" in
 547 Boolean networks. This category allows us to embrace those cases of emergence
 548 that are obviously not biological adaptations, namely phase transitions. However,
 549 it can allow for some discontinuities in the history of life that do not need any
 550 selection as explanation. Those situations are likely to concern the lowest stages
 551 of life, for example, the first emergence of replicators (Fry 1995). Selection is
 552 likely to act, and act powerfully, at highest levels, in ways that strongly counter
 553 those kinds of evolution with no selection.
- 554 B. Computer simulations can display features of natural selection climbing a peak on
 555 an adaptive landscape. In this class fall classical genetic algorithms with fixed fit-
 556 ness function, or some of the Bedau-Packard class II (Echo does not have a fixed
 557 fitness function), or Channon's "artificial evolution." This is the realm of gradual
 558 evolution by cumulative selection; adaptations are continuously produced,¹⁹ but
 559 there will not be many discontinuities, and then few novelties and no open-ended
 560 evolution.
- 561 C. Non-gradual evolution; here emergence, innovations and novelties are not con-
 562 ceivable in terms of cumulative selection, like in the case of those novelties con-
 563 sidered by evo-devo (Carroll 2005). Some maladapted processes ("maladapted"
 564 in the sense of not-fitness-increasing, i.e., no simple "hill climbing") entail new
 565 kinds of adaptation, as the decreases of mean fitness implied by the novelties
 566 named "evolutionary transitions" by Maynard-Smith and Szathmary (1995) or
 567 Michod (1999) (i.e., cohesive groups of entities becoming new units of fitness
 568 (cells, multicellular organisms, colonies)). Interesting cases in this category are
 569 the processes of "compositional evolution," as modeled by Watson (2005) in mod-
 570 ified genetic algorithms that incorporate features proper to sexuality and symbi-
 571 osis in real life. In this class we therefore find Channon's class 3, but also Pattee
 572 and Crutchfield's class III. Robust emergence (in the sense of Sect. 1) clearly
 573 characterizes those features; the pending question is to find subclasses of models
 574 for which a range of parameter values would robustly entail not only m-regulari-
 575 ties between emergent sets of cells or agents, but continuous production of new
 576 m-regularities, or even of new entities supporting novel m-regularities. For the
 577 moment (Bedau et al. 1998) no such thing has been found, although members of
 578 the ALife community are working on it (Taylor 2001).

579 Those categories leave an open question: Is there anything particular with Bedau
 580 and Packard's class III, namely *the history of life*? Is it included, in fact, in my class C

¹⁸ Channon opposes *artificial selection* and *natural selection* as genetic algorithms with a fixed fitness function vs. genetic algorithms with evolving fitness functions.

¹⁹ The problem for populations is to avoid being stacked on a local optimum; hence the shifting balance theory—yet some more recent concepts such as neutral tunnels of fitness (Gavrilets 2003) account for solutions that do not need drift.

(1993)

h s

(Channon and Dangle 2000)

Author Proof

581 here, which would mean that life—in the vernacular sense—has nothing more than all
 582 the features of those processes that are likely to be simulated. Or is there something
 583 more about it?

584 Bedau (1999) argues that for the moment, open-ended unbounded adaptation as
 585 well as increase in complexity which we find in the phanerozoic fossil record is not
 586 reached as a result of the various simulations ~~we~~ currently ~~have~~ available—be they
 587 from class II in his classification or class C of mine. This is just a current fact, and
 588 nothing precludes that some more sophisticated future simulations will yield patterns
 589 of complexity and unbounded adaptation that will match the fossil record's evolu-
 590 tionary pattern (Bedau et al. 1998). The point is that the processes we are acquainted
 591 with, in the sense that we can now implement them in computer simulations, are not
 592 enough to recreate the whole pattern of adaptive radiation or rates of novelties met in
 593 the phylogenic trees. On the other hand we can reproduce increases of complexity that
 594 match the increase of complexity found in the tree of life (Adami et al. 2000), estimat-
 595 ing complexity with some informational-based measures of information (Ofria et al.
 596 2000; Adami 2002). This implies that the Darwinian features (variability, inheritance,
 597 fitness) of the entities used in our computer simulations are enough to produce such
 598 trends towards novelty; ~~however, it means that computational criteria of emergence~~
 599 ~~seem sufficient to account for the whole of life and nature in general.~~ ~~It's not some feature~~

600 Yet, there remains the fact that open-ended adaptive processes, with continuous
 601 emergence of innovations and new kinds of adaptations, characteristic of the Phan-
 602 erozoic record, are not yet reproduced by our simulations. This means that the default
 603 hypothesis of investigations into the processes of long-term biotic evolution is that
 604 transparent ~~pure possible~~ processes—transparent in the sense that they are likely to be
 605 implemented on computers—are not alone responsible for the open-ended adaptive
 606 trend in evolution. The major benefit of this approach is not a definitive statement of
 607 *ignorabimus* but, on the contrary, a firm basis for an empirical approach to such an
 608 issue: Find a way to falsify the default hypothesis, find evidence for a clear and testable
 609 alternative hypothesis, or progressively defeat these alternatives. Such a program is
 610 not at all complete, but is indeed feasible. To this extent, the specificity of novelty in
 611 biological evolution—open-ended evolution, as we say—is still in question; the com-
 612 putational concept of emergence has therefore the virtue of allowing us to formulate
 613 the empirical question about the uniqueness of features of novelty in life.

614 6 Conclusion

615 Emergence is a word whose use exponentially increased in science and in discourses
 616 about science since hard reductionist programs in physics and biology seemed to reach
 617 some limits two decades ago. However, this use is often quite loose, and most of the
 618 time irreducibility and novelty invoked by its tenants are in fact likely to be dissolved
 619 in a reductionist framework, as happened to earlier emergentism of the 1920s. Com-
 620 putational incompressibility, however, provides a concept of emergence likely to resist
 621 such objection, and to be not merely epistemological—which also includes “robust
 622 emergence” as computationally emergent processes that display “m-regularities.” On
 623 this basis one can recapture the other dimensions of what is understood under the name

624 of emergence, namely irreducibility, downward causation (as relations of explanatory
625 constraint) and novelty. Furthermore, robustness analysis of several simulations dis-
626 playing computational emergence entitles one to ascribe the property of emergence
627 to a target system and specify the causally relevant parameters for the emerging fea-
628 tures, so that the concept of emergence can exceed the context of digital processes and
629 simulations and concern the ~~objective~~ world. Hreal

630 Reciprocally, the very idea of predictability is enriched by such an approach. Some
631 systems do not allow predictability, albeit they are deterministic—and such a prop-
632 erty of predictability is ontologically proper to the system, although it concerns an
633 epistemic feature, namely prediction. Computationally emergent systems are not pre-
634 dictable as to the fate of their component elements. Yet robust emergence—in the
635 sense of the arising of sequences displaying counterfactual dependencies (m-regular-
636 ities) between sets of building blocks—allows one to elaborate partial predictions at
637 this macrolevel (m-predictions) as well as M-predictions based on the global relations
638 between sets of outcomes of simulations and ranges of the values of parameters of
639 simulations. The study of complex systems extensively draws on this possibility of
640 forging qualitative macro predictions, and identifying bifurcations between qualita-
641 tive behaviours—sometimes understood as attractors—on the basis of the ranges of
642 values that such bifurcations discriminate. Along those lines, the dimension of nov-
643 elty, proper to the vernacular concept of emergence, can be circumscribed. However,
644 biological evolution displays not only novelties but also increasing trends towards
645 novelties (open-endedness). The rates of producing novelties are themselves proper
646 to some systems, and investigating the conditions for open-ended evolution means
647 investigating the dependency of those rates upon the various parameters proper to bio-
648 logical evolution. It is now an empirical question to decide whether the highest rates
649 of production of novelties, which define open-ended evolution, are within the reach of
650 computer simulations or involve some other features proper to biological evolution.
651 However, the point is that the general concept of computational emergence is instan-
652 tiated by lots of systems, and can be further specified into more refined classes—first,
653 “robust emergence,” and then, degrees of emergence producing more or less high rates
654 of novelty. The present analysis therefore provides a multifaceted objective concept
655 of emergence of which several nuances allow one to ask questions about the varieties
656 of novelty in natural systems in general, and the specificity of novelty in evolutionary
657 biology in particular. H present

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